

Bayesian Influence Functions for Scalable Data Attribution

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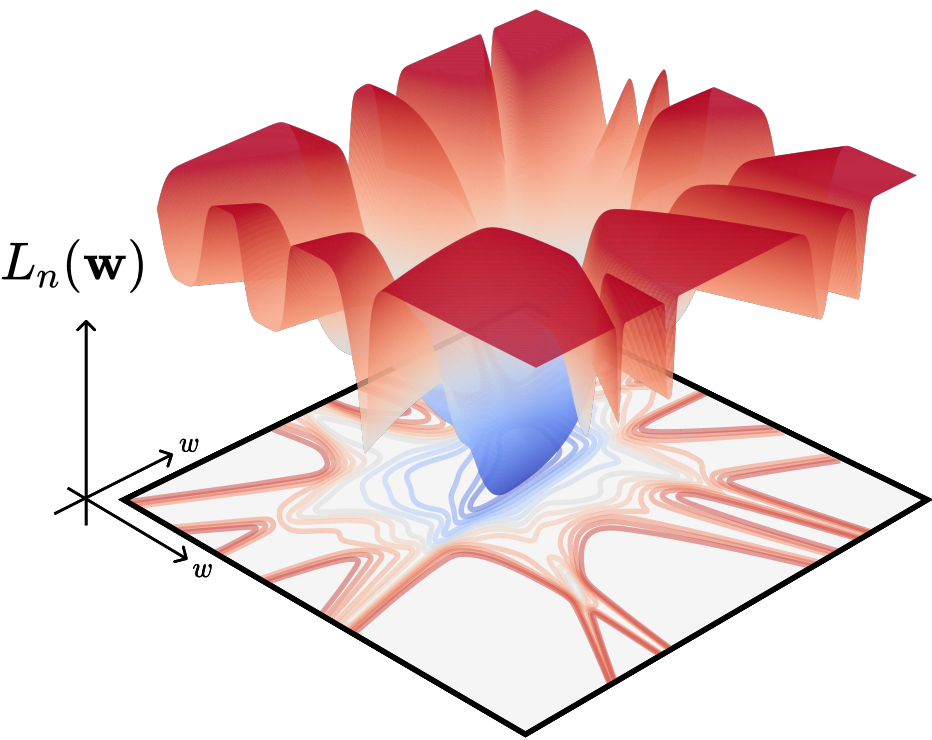
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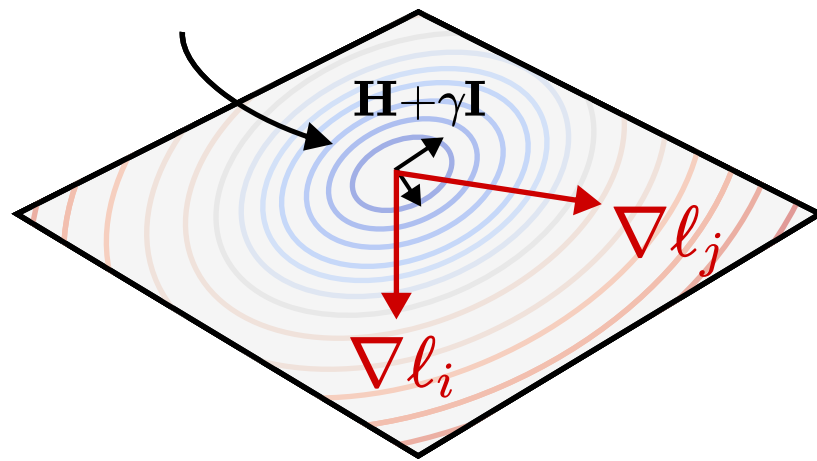
From influence functions (IF) to Bayesian influence functions (BIF): We introduce local Bayesian Influence Functions, which capture higher-order information in loss landscape geometry and can be scaled to models with billions of parameters.



Loss landscape geometry determines how sample i influences behaviour on sample j .

$$\text{IF} = \langle \nabla \ell_i, \nabla \ell_j \rangle (\mathbf{H} + \gamma \mathbf{I})^{-1}$$

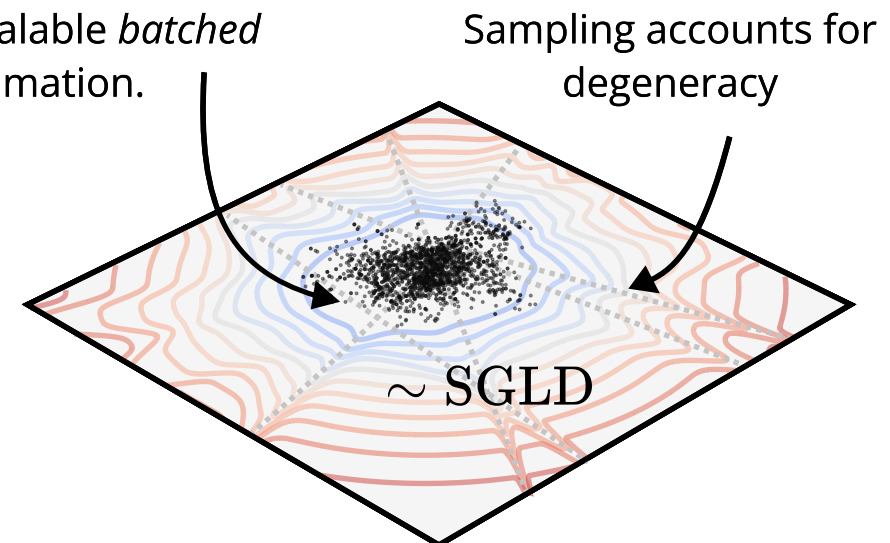
Computing the Hessian exactly is intractable for large models.



(Damped) Influence Functions measure influence via the gradient (first-order) and Hessian (second-order).

$$\text{BIF} = \text{Cov}_\gamma[\ell_i, \ell_j]$$

Gradient-based samplers enable scalable *batched* estimation.



Sampling accounts for degeneracy

(Local) Bayesian Influence Functions measure influence via statistics that are sensitive to higher-order geometry.



1. Theory: Classical to Bayesian

Classical Influence Function

First-order estimate of the effect of training on sample i on an observable ϕ .

$$\text{IF}(\mathbf{z}_i, \phi) := \left. \frac{\partial \phi(\mathbf{w}^*(\beta))}{\partial \beta_i} \right|_{\beta=1}$$

Sample i → Observable → # of copies of sample i → Local Minima

Bayesian Influence Function

Higher-order estimate of the effect of Bayesian updating on sample i on an observable ϕ .

$$\text{BIF}(\mathbf{z}_i, \phi) := \left. \frac{\partial \mathbb{E}_{\text{train}, \beta}[\phi(\mathbf{w})]}{\partial \beta_i} \right|_{\beta=1}$$

Expectation over the local posterior

Often, we're interested in using influence functions to estimate how much sample i effects the loss ℓ on a new sample j

$$= -\nabla_{\mathbf{w}} \ell_j(\mathbf{w}^*)^\top \mathbf{H}_{\mathbf{w}^*}^{-1} \nabla_{\mathbf{w}} \ell_i(\mathbf{w}^*)$$

Gradient on sample i → Inverse Hessian → Gradient on sample j

$$\text{BIF}(\mathbf{z}_i, \ell_j) = -\text{Cov}(\ell_i(\mathbf{w}), \ell_j(\mathbf{w}))$$

Covariance over local posterior

Classical influence functions face several key challenges: How to adapt the IF to non-global minima? How to deal with models that have degenerate loss landscapes (=singular Hessians)? How to scale to models with billions of parameters?



2. Methodology

Bayesian IFs bypass key problems with classical IFs: Unlike classical IFs, which are sensitive only to second-order structure in the loss landscape, the BIF is sensitive to all higher-order interactions in the loss landscape. The BIF can be approximated at scale with SGMCMC, rather than relying on memory-intensive Hessian estimates.

$$\varphi(w) = \mathcal{N}(w^*, \lambda \mathbf{1})$$

Localize at a reference choice of weights

$$\text{Cov}(\ell_i(\mathbf{w}), \ell_j(\mathbf{w}))$$

Approximate with SGMCMC

Localization. We introduce a prior centered at w^* to adapt the BIF to the *local* setting. This allows us to apply the BIF to individual model checkpoints obtained through standard stochastic optimization (e.g., SGD).

Sampling. We introduce a BIF estimator based on stochastic-gradient SGMCMC sampling for scalable *batched* estimation on models with billions of parameters, including large language models.



3. Scaling

The BIF exhibits more favorable scaling in *model size* than approximations of the classical IF like EK-FAC. However, EK-FAC still currently outperforms the BIF in scaling in *data size* when evaluated on predicting the results of retraining experiments.

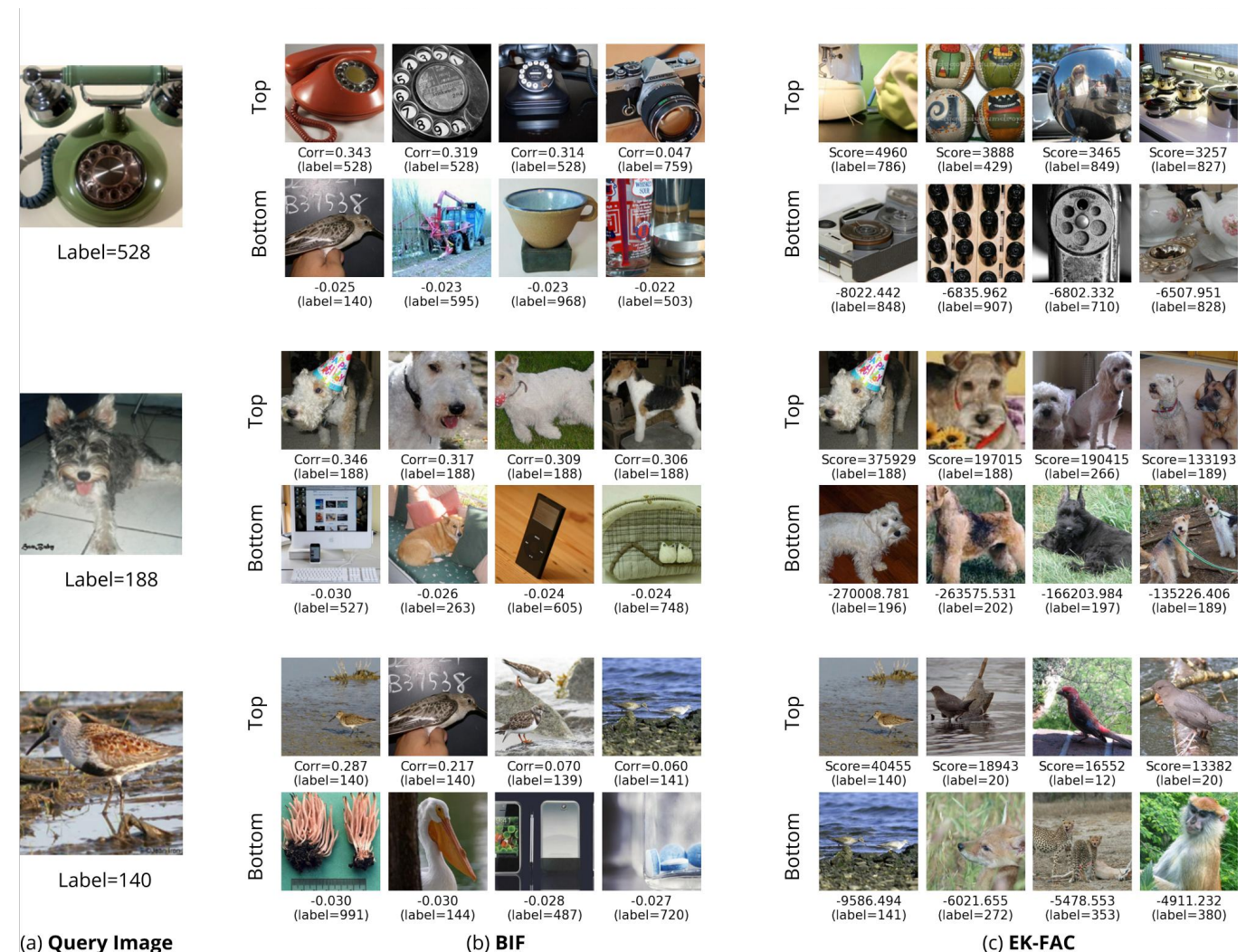


4. Applications

The BIF reveals interpretable data attribution patterns while often scaling more favorably than inverse Hessian-based methods.



3,000+ examples



Qualitative comparison shows BIF yields similar high-influence samples to EK-FAC for Inception-v1. Left are query images; center are high-BIF samples; right are EK-FAC.

Le quiz **avait** dix questions, et **elle** en a **rép**ondu correctement ...

elle → The quiz had 10 questions, and **she** answered 8 correctly.

avait → The quiz **had** 10 questions, and she answered 8 correctly.

rép → The quiz had 10 questions, and she **answered** 8 correctly.

answered = répondu

A team in **Brazil** discovered the

→ After moving to **Germany**, she quickly

→ The reef systems around **Australia** are

→ In **Morocco**, market vendors often offer

→ The recipe, popular in **Italy**, uses

1	3	5	7	9	11	13	15	17	19	21
1	0	2	4	6	8	10	12	14	16	18
3	0	2	4	6	8	10	12	14	16	18
5	0	2	4	6	8	10	12	14	16	18
7	0	2	4	6	8	10	12	14	16	18
9	0	2	4	6	8	10	12	14	16	18
11	0	2	4	6	8	10	12	14	16	18
13	0	2	4	6	8	10	12	14	16	18
15	0	2	4	6	8	10	12	14	16	18
17	0	2	4	6	8	10	12	14	16	18
19	0	2	4	6	8	10	12	14	16	18
21	0	2	4	6	8	10	12	14	16	18

☐ Query Token → Is Correlated With Each Token In The → Target Sequence

■ Positive Correlation / Negative Influence

■ Negative Correlation / Positive Influence

The per-token BIF detects related tokens in Pythia-2.8b.

The loss-covariance formula straightforwardly generalizes to a per-token loss covariance. We use this per-token BIF to study the influence of individual tokens on other tokens. This provides a tool for identifying tokens that behave similarly.



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Full Paper:

